

# NECESSARY BEST ESTIMATORS IN CERTAIN CLASSES OF LINEAR ESTIMATORS FOR IKEDA-SEN SAMPLING

By

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## 1. INTRODUCTION

Let a population consist of a finite number  $N$  of units. For estimating the population total

$$T = \sum_{i=1}^N x_i$$

Horvitz & Thompson [6] introduced three classes of linear estimators. Godambe [4] formulated his most general class of linear estimator in addition to Horvitz—Thompson's estimators and proved the non-existence of Minimum variance Linear Unbiased estimator (MVLUE) in his most general class. Koop [7] following the logic of Horvitz—Thompson gave an axiomatic system of sample formation and defined seven classes of linear estimators, within which almost all the linear unbiased estimators of the population total lie. He examined the Godambe's formulation and commented on page 91 of his paper as follows:

"Godambe [4] formulated four classes of estimators of  $T$  viz. what in this system of notations turns out to be  $T_1, T_2, T_6$ , and  $T_5$  (his most general estimator) without posting the three features of sample formation as axioms...The advantage of the systematic approach, having its being in the axioms, is that three more classes, including  $T_7$  which is more general than Godambe's  $T_5$  have been brought to light'.

Further Koop gave a proof that the best linear unbiased estimator does not exist in the most general class ( $T_7$ ) of linear estimators.

Thus while estimating the population total, if the MVLUE does not exist the use of the 'necessary best' estimators' (NBE) was

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recommended by Prabhu-Ajgaonkar [1], as serviceable estimators purely from the practical point of view. He [2] defined the higher order NBE's as follows:

Let  $C$  be a class linear unbiased estimators and  $t'$  belong to  $C$ , then it is easily seen that the variance of  $t'$  can be expressed in the following form:

$$\text{Var}(t') = \sum_{i=1}^N A_{ii} Y_i^2 + \sum_{i \neq j=1}^N A_{ij} Y_i Y_j \quad \dots(1.1)$$

Where the quantities  $A_{ij}$  ( $i, j=1, 2, \dots, N$ ) involve the known functions of probabilities and coefficients of the class.

Further let  $t'_1$  be another unbiased estimator belonging to the class  $C$  and that the variance of  $t'_1$  be given by

$$\text{Var}(t'_1) = \sum_{i=1}^N b_{ii} Y_i^2 + \sum_{i \neq j=1}^N b_{ij} Y_i Y_j \quad \dots(1.2)$$

consider the quantity

$$\begin{aligned} Q &= \text{Var}(t'_1) - \text{Var}(t') \\ &= \sum_{i=1}^N (A_{ii} - b_{ii}) Y_i^2 + \sum_{i \neq j=1}^N (A_{ij} - b_{ij}) Y_i Y_j \end{aligned}$$

obtained from equations (1.1) and (1.2)

*Definition:* The estimator  $t'_1$  is a necessary best estimator of order  $r$  for the class  $C$  if for every  $t'$  in  $C$  principal minors of expressions of the form  $Q$  upto the order  $r$ , are positive. Prabhu-Ajgaonkar [2] says "The necessary best estimator of the first order minimises the variance of the population for which  $Y_1 \neq 0$  and  $Y_i = 0, i=2, 3, \dots, N$ . Similarly a necessary best estimator of the second order is obtained by minimising  $V(t)$  for the population vector for which  $Y_1 \neq 0, Y_2 = 0$  but  $Y_i = 0$  for  $i=3, 4, \dots, N$ . Further he proved the existence of second order NBE in the most general class and NBE is the same as that of Horvitz-Thompson estimator; which is infact not true as remarked by Rao [9]. This has been established by Yogi and Gupta [11] utilising the approach of obtaining first and second order NBE of the author (1969) and further proved the non-existence of second and higher order NBE in  $T_3, T_4, T_5$  and  $T_6$  classes of linear unbiased estimators.

Prabhu-Ajgaonkar [3], while considering the Ikeda Sen system of sampling proved the existence of NBE of order one in  $T_2$  and  $T_4$  classes of linear estimators. In the present paper the authors have investigated the non-existence of second and higher order NBE's in  $T_4$ ,  $T_5$  and  $T_6$  classes of linear estimators when Ikeda-Sen (1952) system of sampling is undertaken, following the same approach as in the author's earlier paper (1969).

### 1. IKEDA-SEN SAMPLING SCHEME

A sampling procedure was proposed by Ikeda, a student of Midzuno and the procedure was then generalised by Midzuno [8] Sen [10] independently gave the identical system of sampling and hence in view of these facts the present sampling system is referred to as Ikeda-Sen sampling Scheme. The scheme consists in drawing the first unit of the sample with probability proportional to size and the rest of the  $(n-1)$  units with equal probability without replacement from the remaining  $(N-1)$  units of the population.

In the above sampling procedure, the probability of drawing  $i$ th unit at  $r$ th draw and the probability of selecting  $i$ th unit at the  $r$ th draw and  $j$ th unit at the  $s$ th draw are respectively given by

$$P[(X_r = X_i)] = P_{ir} = \begin{cases} P_i & \text{for } r=1 \\ \frac{1-p_i}{N-1} = C_i & \text{for } r=2, 3, \dots, N \end{cases} \quad \dots(2.1)$$

$$P(X_r = X_i \text{ and } X_s = X_j)$$

$$= p(i, j) = \begin{cases} \frac{p_i}{N-1} & \text{when } r=1 \text{ and } s \geq 2 \\ \frac{1-p_i-p_j}{(N-1)(N-2)} & \text{when } r, s \geq 2 \end{cases} \quad \dots(2.2)$$

We know that

$$S = \binom{N}{n} n! \quad \dots(2.3)$$

is the total number of ordered samples of size  $n$  from the population of size  $N$  in without replacement sampling. Then the probability of the  $i$ th sample in which the  $i$ th ( $i=1, 2, \dots, N$ ) unit appears at the first draw is given by

$$\frac{P_i}{\binom{N-1}{n-1} (n-1)!} = k_i \text{ (say)} \quad \dots(2.4)$$

Also we define the following

$$k = \binom{N-1}{n-1} (n-i)! \quad \dots(2.5)$$

is the number of samples in which the first place in the sample is fixed for  $i$ th ( $i=1, 2, \dots, N$ ) unit.

$$k' = \binom{N-2}{n-2} (n-1)! \quad \dots(2.6)$$

is the number of samples in which  $j$ th ( $\neq i$ ) unit appears at the first draw and the  $i$ th unit appears anywhere else in the sample.

### 3. NECESSARY BEST ESTIMATORS IN $T_6$ CLASS

The Ikeda-Sen estimator in this class for the population total  $T$  is defined as

$$T_6^M = \sum_{r=1}^n \beta_r^t x_r \quad \dots(3.1)$$

where  $\beta_r^t$  is the weight associated to the  $r$ th draw of the  $i$ th sample

$$E \left( T_6^M \right) = \sum_{i=1}^N \sum_{r=1}^n \sum_{t \supset i_r} \beta_r^t (x_r = x_i) k_i \quad \dots(3.2)$$

collecting the coefficients of each  $x_i$ , the expression in equation (3.2) can be written as,

$$\begin{aligned} & x_1 \left[ K_1 \sum_{t \supset 1_1} \beta_1^t + k_2 \left( \sum_{t \supset (2_1, 1_2)} \beta_2^t + \sum_{t \supset (2_1, 1_3)} \beta_3^t + \dots + \sum_{t \supset (2_1, 1_n)} \beta_n^t \right) \right. \\ & \quad + k_3 \left( \sum_{t \supset (3_1, 1_2)} \beta_2^t + \sum_{t \supset (3_1, 1_3)} \beta_3^t + \dots + \sum_{t \supset (3_1, 1_n)} \beta_n^t \right) \\ & \quad \left. + \dots + K_N \left( \sum_{t \supset (N_1, 1_2)} \beta_2^t + \sum_{t \supset (N_1, 1_3)} \beta_3^t + \dots + \sum_{t \supset (N_1, 1_n)} \beta_n^t \right) \right] \\ & + x_2 \left[ K_2 \sum_{t \supset (2_1)} \beta_2^t + k_1 \left( \sum_{t \supset (1_1, 2_2)} \beta_2^t + \sum_{t \supset (1_1, 2_3)} \beta_3^t + \dots + \sum_{t \supset (1_1, 2_n)} \beta_n^t \right) \right. \\ & \quad \left. + \dots + K_N \left( \sum_{t \supset (N_1, 2_2)} \beta_2^t + \dots + \sum_{t \supset (N_1, 2_n)} \beta_n^t \right) \right] \end{aligned}$$

$$\begin{aligned}
 &+ x_n \left[ K_N \sum_{t \supset N_1} \beta_N^t + K_1 \left( \sum_{t \supset (1_1, N_2)} \beta_2^t + \sum_{t \supset (1_1, N_3)} \beta_3^t + \dots + \sum_{t \supset (1_{11}, N_n)} \beta_n^t \right) \right. \\
 &\quad \left. + \dots + K_{N-1} \left( \sum_{t \supset [(N-1)_1, N_2]} \beta_2^t + \dots + \sum_{t \supset [(N-1)_1, N_n]} \beta_n^t \right) \right] \dots (5.3)
 \end{aligned}$$

where the summation have the following meaning.

$$(i) \quad \sum_{t \supset i_1} \beta_1^t$$

is the sum of all those weights associated to the first draw and to the  $i$ th sample in which  $i$ th unit appears at the first draw.

$$(ii) \quad \sum_{t \supset (j_1, i_r)} \beta_r^t \quad \text{for } j=1, 2, \dots, N$$

$(i \neq j)=1, 2, \dots, N$  and  $r=1, 2, \dots, n$  is the sum of all those weights associated to the  $r$ th draw and to the  $l$ th sample in which  $j$ th unit appears at the first draw and  $i$  ( $\neq j$ )th unit appears at the  $r$ th draw.

The conditions of unbiasedness of  $\left( T_6^M \right)$  for the population total  $T$  can be easily had from the equation (3.3) by equating the bracketed terms to unity. Let us denote them by

$$[i] \quad \text{for } i=1, 2, \dots, N \quad \dots (3.4)$$

Further

$$V \left( T_6^M \right) = E \left( T_6^M \right)^2 - T^2 \quad \dots (3.5)$$

Thus to minimize  $V \left( T_6^M \right)$  subject to the conditions of unbiasedness in equation (3.4) ; we consider the function  $\phi_1$  as follows

$$\begin{aligned}
 \phi_1 = &x_1^2 \left[ K_1 \sum_{t \supset (1_1)} \left( \beta_1^t \right)^2 + k_2 \left( \sum_{t \supset (2_1, 1_2)} \left( \beta_2^t \right)^2 + \dots \right. \right. \\
 &+ \sum_{t \supset (2_1, 1_n)} \left( \beta_n^t \right)^2 + K_3 \left( \sum_{t \supset (3_1, 1_2)} \left( \beta_2^t \right)^2 + \sum_{t \supset (3_1, 1_3)} \left( \beta_3^t \right)^2 + \dots \right. \\
 &\left. \left. + \sum_{t \supset (3_1, 1_n)} \left( \beta_n^t \right)^2 + \dots + K_N \left( \sum_{t \supset (N_1, 1_2)} \left( \beta_2^t \right)^2 + \dots + \sum_{t \supset (N_1, 1_n)} \left( \beta_n^t \right)^2 \right) \right]
 \end{aligned}$$



when  $t \supset (2_1) \dots, \beta_2^t$

when  $t \supset (3_1, 2_2) \dots, \beta_n^t$

when  $t \supset (3_1, 2_n) \dots, \beta_1^t$

when  $t \supset N_t, \beta_2^t$

when  $t \supset (N_t 2_2); \beta_n^t$

when  $t \supset (N_1, 1_n)$

and then

equating the differential coefficients to zero we get a set of equations. The  $n$  considering the vector  $X=(x_1 \neq 0, x_i=0; i=2, 3, \dots, N)$  and the above equations so obtained and making use of proper sums, along with the conditions of unbiasedness we get,

$$\lambda_1 = \frac{x_1^2}{\pi_1} \dots(3.6)$$

Substituting the value of  $\lambda_1$  in the above equation we get

$$\beta_r^t = \frac{1}{\pi_1} = 0 \dots(3.8)$$

for all samples which include first unit at any draw for  $r=1, 2 \dots, n$

Now if we consider the population vector  $X=(x_1 \neq 0, x_2 \neq 0$  and  $x_i=0; i=3, 4, \dots, N)$  and making use of equations (3.7) and (3.8) and the first equation of the differentials we get

$$\sum_{r=1}^n \beta_r^t = 0 \dots(3.9)$$

for those samples containing 1st unit at the first draw. But from equation (3.8) each  $\beta_r^t$  is greater than zero. Thus (3.8) and (3.9) suggest that

$$\beta_r^t = 0 \text{ for all } r \text{ and for } t \supset 1_1 \dots(3.10)$$

which is a contradiction to the existence of NBE of order one and hence it proves that NBE of order two under  $T_3$  class of linear estimators does not exist when Ikeda-Sen sampling scheme is adopted.

#### 4. NECESSARY BEST ESTIMATORS IN $T_4$ AND $T_5$ CLASSES

The Ikeda-Sen estimator for population total  $T$  in cases of  $T_4$  and  $T_5$  classes of Linear Estimators is defined respectively as:

$$T_4^M = \sum_{r=1}^n \beta_{ir} x_r \quad \dots(4.1)$$

and

$$T_5^M = \sum_{i=1}^n \beta_i^t x_i \quad \dots(4.2)$$

where  $\beta_{ir}$  is the weight associated to the  $i$ th unit, whenever it appears at the  $r$ th draw and  $\beta_i^t$  is the weight associated to the  $i$ th unit whenever it is included in the  $t$ th sample.

The conditions of unbiasedness for  $T_4^M$  for population total in  $T_4$  class can be seen as

$$= (B_{i1} p_1 + \sum_{r=2}^n c_r B_{ir}) = 1 \quad \dots(4.3)$$

for all  $i=1, 2, \dots, N$

where as the conditions of unbiasedness for  $T_5^M$  for the population total in  $T_5$  class are

$$[g_i] = K_i \sum_{t \supset i_1}^N \beta_i^t + \sum_{j(\neq i)=1}^n K_j \sum_{t \supset j_1} \beta_j^t \quad \dots(4.4)$$

For  $i=1, 2, \dots, N$ .

The results similar to that of  $T_6$  class can be easily proved for  $T_4$  and  $T_5$  classes, following the same routine algebra. The outlines



of the proof are however, given below:

1. Obtain the variance expressions

$$V \left( T_4^M \right) \text{ and } V \left( T_5^M \right)$$

2. For minimization of  $V \left( T_4^M \right)$  w.r.t. the conditions in equation (4.3), define the function

$$\phi_2' = V \left( T_4^M \right) - 2 \sum_{i=1}^N \lambda_i (q_i - 1),$$

- and for minimization of  $V \left( T_5^M \right)$  w.r.t. the conditions in equation (4.4), define the function

$$\phi_3' = V \left( T_5^M \right) - 2 \sum_{i=1}^N \lambda_i' (g_i - 1).$$

where  $\lambda_i$  are the Lagrangian undetermined multipliers.

3. Define functions  $\phi_2$  from  $\phi_2'$  and  $\phi_3$  from  $\phi_3'$  containing the terms involving  $x_1$   $x_2$  only. The so obtained functions will be of the following form,

$$\begin{aligned} \phi_2 = & x_1^2 \sum_{r=1}^n \beta_{1r}^2 p_{1r} + x_1 x_2 \sum_{s(\neq r)=1}^n \beta_{1r} \beta_{2s} p(1r, 2s) \\ & + x_2^2 \sum_{r=1}^n \beta_{2r}^2 p_{2r} + x_1 x_2 \sum_{s(\neq r)=1}^n \beta_{2r} \beta_{1s} p(2r, 1s) - 2 \sum_{i=1}^2 (q_i - 1) \end{aligned}$$

and

$$\phi_3 = x_1^2 \left[ K_1 \sum_{t \supset 1_1}^K \left( \beta_1^t \right)^2 + K_2 \sum_{t \supset 2_1}^{K_1} \left( \beta_1^t \right)^2 + \dots + K_N \sum_{t \supset N_1}^{K_1} \left( \beta_1^t \right)^2 \right]$$

$$\begin{aligned}
 & +x_2^2 \left[ K_2 \sum_{t \supset 2_1}^K \left( \beta_2^t \right)^2 + K_1 \sum_{t \supset 1_1}^{K'} \left( \beta_2^t \right)^2 + \dots + K_N \sum_{t \supset N_1}^{K'} \left( \beta_2^t \right)^2 \right] \\
 & 2x_1x_2 \left[ K_1 \sum_{t \supset (1_1, 2)} \beta_1^t \beta_2^t + K_2 \sum_{t \supset (2_1, 1)} \beta_2^t \beta_1^t + K_3 \sum_{t \supset (3_1, 1, 2)} \beta_2^t \beta_1^t + \dots \right. \\
 & \left. + K_N \sum_{t \supset (N_1, 1, 2)} \beta_2^t \beta_1^t \right] - 2 \sum_{i=1}^{-2} \lambda_i^1 (g_i - 1)
 \end{aligned}$$

where

$$\sum_{t \supset (i_1, j)}$$

is the sum over those weights of all the samples in which  $i$ th unit appears at the first draw and the  $j$ th unit appears anywhere in the samples.

$$\sum_{t \supset (j_1, 1, 2)}$$

is the sum over those weights of all the samples in which  $j$ th ( $j \neq 1, 2$ ) unit appears at the first draw and first and second units appear anywhere in the samples.

4. Differentiate  $\phi_2$  and  $\phi_3$  w.r.t. the weighting coefficients involved in them and equate the differential coefficients to zero. Making the appropriate sums and using the population vector  $X = (x_1 \neq 0, x_i = 0 \text{ for } i = 2, 3, \dots, N)$

One would get,

$$B_{1r} = \frac{1}{\pi_1} \text{ (in } T_4 \text{ case) for all } r = 1, 2, \dots, n$$

$$B_1^t = \frac{1}{\pi_1} \text{ (in } T_5 \text{ case) for all } t = 1, 2, \dots, K$$

This proves the existence of NBE of order one in  $T_4$  &  $T_5$  classes of linear unbiased estimators.

Also by utilizing the population vector

$X=(x_1=0 \ x_2=0 \ x_i=0 \ \text{for } i=3, 4, \dots, N)$  and the appropriate sums, one would get,

$$\beta_{1r}=0 \ (\text{in } T_4 \ \text{case}) \ \text{for all } r=1, 2, \dots, n$$

$$\beta_1^t=0 \ (\text{in } T_5 \ \text{case}) \ \text{for all } t=1, 2, \dots, K$$

This leads to contradiction that all the weighting coefficients are zero and hence proves the non-existence of NBE of order two in  $T_4$  and  $T_5$  classes of linear unbiased estimators under Ikeda-Sen sampling scheme,

#### REMARKS

Since MVLUE is the NBE of order  $N$ , the results of sections 3, and 4 suggest that the MVLUE in  $T_4$ ,  $T_5$  and  $T_6$  classes of linear estimators does not exist when Ikeda-Sen system of sampling is being employed.

#### SUMMARY

The non-existence of necessary best estimators of order two has been established in  $T_4$ ,  $T_5$  and  $T_6$  classes of linear estimators when Ikeda-Sen sampling Scheme is undertaken.

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